

# THE INVERSE PROBLEM FOR SMALL RANDOM PERTURBATIONS OF DYNAMICAL SYSTEMS

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## ABSTRACT

What can one get to know about the dynamical system from its small random perturbation? What can one say about solutions of an ordinary differential equation  $\dot{x}_t = B(x_t)$  having some information on its singular perturbation operator  $L^\varepsilon = \varepsilon L + (B, \nabla)$  with  $L$  being an elliptic second order operator? These problems are studied in the paper.

## 1. Introduction

Let  $S^t$  be a continuous in  $t$  group of homeomorphisms (the flow) of a complete metric locally compact space  $X$  with  $t$  being a continuous parameter  $-\infty < t < \infty$  or a discrete one  $t = \dots, -2, -1, 0, 1, 2, \dots$ .

Consider a family of time-homogeneous Markov processes  $x_t^\varepsilon$  in  $X$  with continuous trajectories, where  $\varepsilon$  is a positive parameter. Let  $P^\varepsilon(t, x, V)$  be the transition probability of  $x_t^\varepsilon$  and suppose that all  $x_t^\varepsilon$  satisfy the Feller property (see [2]), i.e., for any continuous function  $f$  on  $X$  the function  $P_t^\varepsilon f$  defined by

$$(1.1) \quad P_t^\varepsilon f(x) = \int_X P^\varepsilon(t, x, dy) f(y)$$

is also continuous.

The family  $x_t^\varepsilon$  is called a small random perturbation of the dynamical system  $S^t$  if for any continuous  $f$  and all  $t > 0$ ,

$$(1.2) \quad \sup_{x \in X} |P_t^\varepsilon f(x) - f(S^t x)| \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

We distinguish two general problems about small random perturbations of dynamical systems. The first one is the direct problem, i.e., the study of

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asymptotic behaviour as  $\varepsilon \rightarrow 0$  of parameters of the process  $x_t^\varepsilon$  provided some information about the dynamical system  $S'$  and the type of perturbations are known. The second one is the inverse problem, i.e., the study of the dynamical system  $S'$  when the asymptotic behaviour as  $\varepsilon \rightarrow 0$  of some probabilistic parameters of the processes  $x_t^\varepsilon$  is known.

Most papers on this matter deal with the direct problem (see, for instance, [2] and [7]). Some papers can be considered as dealing with both kinds of problems (see [4] and [6]). An example of the inverse problem is given by the Hasminskii's lemma (see [3]). It claims that if  $\mu^\varepsilon$  is an invariant measure of the process  $x_t^\varepsilon$  and for some sequence  $\varepsilon_i \rightarrow 0$  there is a weak limit

$$(1.3) \quad (w) \lim_{\varepsilon_i \rightarrow 0} \mu^{\varepsilon_i} = \mu$$

then  $\mu$  is an invariant measure of the dynamical system  $S'$ .

In this paper we consider other examples of the inverse problem which have applications to the elliptic singular perturbation problem in the theory of partial differential equations.

Let there be given a bounded connected open set  $G \subset X$  with the boundary  $\partial G$ . Denote by  $\tau$  the exit time from  $G$ , i.e.,

$$(1.4) \quad \tau = \inf\{t \geq 0 : x_t^\varepsilon \notin G\}.$$

As usual, denote by  $P_x^\varepsilon\{A\}$  and  $E_x^\varepsilon\xi$  the probability of the event  $A$  and the expectation of the random value  $\xi$ , respectively, for the process  $x_t^\varepsilon$  starting at  $x$ .

We shall prove that the asymptotic behaviour as  $t \rightarrow \infty$  and  $\varepsilon \rightarrow 0$  of  $P_x^\varepsilon\{\tau > t\}$  and  $E_x^\varepsilon\tau$  determines whether the dynamical system  $S'$  has a closed invariant set in  $G \cup \partial G$  or not. Under some conditions the asymptotic behaviour of  $P_x^\varepsilon\{\tau > t\}$  is determined by the asymptotics of the principal eigenvalue of the operator  $P_t^\varepsilon$  defined by (1.1).

When  $x_t^\varepsilon$  is the diffusion perturbation of the smooth dynamical system  $S'$  then we shall find the connection between the existence of the invariant set of the dynamical system  $S'$  in  $G \cup \partial G$  and the asymptotic behaviour of the principal eigenvalue and the solution of the Poisson boundary value problem for the corresponding elliptic singularly perturbed operator.

## 2. The general case

A set  $\Lambda(G) \subset G \cup \partial G$  is called the maximal invariant (under the action of  $S'$ ) set in  $G \cup \partial G$  if any set  $\Omega$  satisfying the property

$$(2.1) \quad S^t \Omega = \Omega \subset G \cup \partial G \quad \text{for all } t \in (-\infty, \infty) \text{ is a subset of } \Lambda(G),$$

i.e.,  $\Omega \subset \Lambda(G)$ . Obviously,  $\Lambda(G)$  is a closed set (maybe empty).

The main result is the following theorem.

**THEOREM 2.1.** (a) *If for some  $x \in G$ ,*

$$(2.2) \quad \limsup_{\epsilon \rightarrow 0} \limsup_{t \rightarrow \infty} \frac{1}{t} \ln P_x^{\epsilon} \{ \tau > t \} > -\infty,$$

*then the maximal invariant set  $\Lambda(G)$  is not empty;*

(b) *If for some  $x \in G$ ,*

$$(2.3) \quad \limsup_{\epsilon \rightarrow 0} E_x^{\epsilon} \tau = \infty,$$

*then the set  $\Lambda(G)$  is not empty.*

**PROOF.** Suppose that  $\Lambda(G)$  is empty. Then there is an open bounded domain  $\tilde{G} \supset G \cup \partial G$  such that the corresponding set  $\Lambda(\tilde{G})$  is also empty.

Indeed, it is easy to see that if  $G_1 \subset G_2$  then  $\Lambda(G_1) \subset \Lambda(G_2)$ . Take the sequence  $\{G_m\}$  of open domains such that

$$(2.4) \quad G_1 \supset G_2 \supset G_3 \cdots \quad \text{and} \quad \bigcap_{m \geq 1} G_m = G \cup \partial G.$$

If  $\Lambda(G_m) \neq \emptyset$  for all  $m \geq 1$  then

$$(2.5) \quad \Lambda = \bigcap_{m \geq 1} \Lambda(G_m) \neq \emptyset$$

since  $\Lambda(G_m)$  is closed and  $\Lambda(G_1) \supset \Lambda(G_2) \supset \Lambda(G_3) \supset \cdots$ .

It is clear that  $\Lambda$  is invariant with respect to  $S^t$  and  $\Lambda \subset G \cup \partial G$ . Thus  $\phi \neq \Lambda \subset \Lambda(G)$ . This contradicts our assumption and we conclude that for some  $m_0 \geq 1$ ,

$$\Lambda(G_{m_0}) = \emptyset.$$

It remains to set  $\tilde{G} = G_{m_0}$ .

For any  $x \in \tilde{G} \cup \partial \tilde{G}$  put

$$(2.6) \quad t(x) = \inf \{ t \geq 0 : S^t x \notin \tilde{G} \cup \partial \tilde{G} \}.$$

Let us prove that

$$(2.7) \quad t(x) < \infty \quad \text{for each } x \in \tilde{G} \cup \partial \tilde{G}.$$

Indeed, if  $t(x_0) = \infty$  then  $S^t x_0 \in \tilde{G} \cup \partial \tilde{G}$  for all  $t \geq 0$ . Thus for some sequence  $t_n \uparrow \infty$  and a point  $y \in \tilde{G} \cup \partial \tilde{G}$  one has

$$S^{t_n} x_0 \rightarrow y \quad \text{as } t_n \uparrow \infty.$$

Then also

$$S^{t_n+t} x_0 \rightarrow S^t y \quad \text{as } t_n \uparrow \infty \quad \text{for any } t \in (-\infty, \infty).$$

One easily obtains from here that  $S^t y \in \tilde{G} \cup \partial \tilde{G}$  for all  $t \in (-\infty, \infty)$  and so the set  $\{S^t y, t \in (-\infty, \infty)\} \subset \Lambda(\tilde{G}) = \emptyset$ . This contradiction proves (2.7).

From the upper semicontinuity of  $t(x)$  we conclude that

$$(2.8) \quad T = \sup_{x \in \tilde{G} \cup \partial \tilde{G}} t(x) < \infty.$$

Notice that (1.2) implies the following condition:

$$(2.9) \quad \limsup_{\varepsilon \rightarrow 0} \sup_{x \in G} P_x^\varepsilon \{\text{dist}(x_t^\varepsilon, S^t x) > \delta\} = 0 \quad \text{for any } \delta > 0 \quad \text{and } t > 0.$$

Now by (2.6)–(2.9) one easily obtains that

$$(2.10) \quad \rho(\varepsilon) = \sup_{x \in G} P_x^\varepsilon \{\tau > T\} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

By the Markov property (see [2]),

$$(2.11) \quad \begin{aligned} P_x^\varepsilon \{\tau > mT\} &= E_x^\varepsilon \chi_{\tau > T} E_{x_T^\varepsilon}^\varepsilon \chi_{\tau > T} \cdots E_{x_{(m-1)T}^\varepsilon}^\varepsilon \chi_{\tau > T} \\ &\leq [\rho(\varepsilon)]^m, \end{aligned}$$

where  $\chi_A$  is the indicator of the event  $A$ .

Since  $P_x^\varepsilon \{\tau > t\}$  decreases in  $t$  then we get

$$(2.12) \quad Q_x^\varepsilon = \limsup_{t \rightarrow \infty} \frac{1}{t} \ln P_x^\varepsilon \{\tau > t\} \leq \frac{1}{T} \ln \rho(\varepsilon).$$

Taking into account (2.10) one concludes by (2.12) that for any  $x \in G$ ,

$$(2.13) \quad Q_x^\varepsilon \rightarrow -\infty \quad \text{as } \varepsilon \rightarrow 0$$

that contradicts (2.2). Thus our assumption that  $\Lambda(G) = \emptyset$  is inconsistent.

To prove the item (b) notice that

$$(2.14) \quad E_x^\varepsilon \tau \leq T \sum_{m=1}^{\infty} P_x^\varepsilon \{\tau > (m-1)T\}.$$

Assumption  $\Lambda(G) = \emptyset$  gives, in view of (2.10), (2.11) and (2.14) for  $\varepsilon$  small enough and  $x \in G$ , that

$$(2.15) \quad E_x^\varepsilon \tau \leq T \sum_{m=1}^{\infty} [\rho(\varepsilon)]^{m-1} < \infty.$$

This contradiction with (2.3) completes the proof of Theorem 2.1.

**3. Diffusion perturbation and application to the elliptic singular perturbation problem**

Let  $X$  be the Euclidean space  $R^n$  and  $x_t^\varepsilon$  be a diffusion process in  $R^n$  generated by the elliptic differential operator of the second order

$$(3.1) \quad L^\varepsilon = \varepsilon^2 L + (B, \nabla), \quad \nabla = \left( \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right),$$

with smooth coefficients, where  $L$  is a nondegenerate elliptic operator and

$$(3.2) \quad \frac{d(S'x)}{dt} = B(S'x).$$

Assume that the bounded domain  $G$  has smooth boundary  $\partial G$ . Under these circumstances, by lemma 3.1 of [5] one obtains that for any  $x \in G$  there is a limit

$$(3.3) \quad \lambda^\varepsilon = \lim_{t \rightarrow \infty} \frac{1}{t} \ln P_x^\varepsilon \{ \tau > t \},$$

where  $\tau$  is defined by (1.4) and  $\lambda^\varepsilon$  turns out to be the principal eigenvalue of the Dirichlet problem for the operator  $L^\varepsilon$  in the domain  $G$ .

Under assumptions of this paragraph we can improve the first part of Theorem 2.1 in the following way.

**THEOREM 3.1.** *The dynamical system  $S^t$  has no invariant set in  $G \cup \partial G$ , i.e.,  $\Lambda(G) = \emptyset$ , if and only if*

$$(3.4) \quad \lim_{\varepsilon \rightarrow 0} \lambda^\varepsilon = -\infty.$$

**PROOF.** If  $\Lambda(G) = \emptyset$  then by Theorem 2.1 we get  $\limsup_{\varepsilon \rightarrow 0} \lambda^\varepsilon = -\infty$  and so  $\lim_{\varepsilon \rightarrow 0} \lambda^\varepsilon = -\infty$ . This follows also from the paper [8].

Suppose now that (3.4) is true and prove that  $\Lambda(G) = \emptyset$ . To do this we assume that  $\Lambda(G) \neq \emptyset$  and prove that

$$(3.5) \quad \limsup_{\varepsilon \rightarrow 0} \lambda^\varepsilon > -\infty.$$

We shall see that, in fact, also

$$(3.6) \quad \liminf_{\varepsilon \rightarrow 0} \lambda^\varepsilon > -\infty,$$

if we assume  $\Lambda(G) \neq \emptyset$ .

Set  $G_\rho = \{x \in G : \text{dist}(x, \partial G) > \rho\}$ ,  $U_\rho(z) = \{y : |z - y| < \rho\}$ , and denote by  $\mathcal{O}$  the origin.

Let  $x \in \Lambda(G)$ , i.e.,  $S^t x \in G \cup \partial G$  for all  $t$ . It is easy to see that one can find positive numbers  $\varepsilon_0, \delta, r_2 < r_1 < 1$  and some points  $Q_m \in U_2(\mathcal{O})$ ,  $m = 0, 1, 2, \dots$ , such that the balls  $V_m^{(1)} = U_{r_1}(Q_m)$  and  $V_m^{(2)} = U_{r_2}(Q_m)$  satisfy for all  $m = 0, 1, 2, \dots$  the following properties:

- (i)  $U_2(\mathcal{O}) \supset V_m^{(1)} \supset (V_m^{(2)} \cup \partial V_m^{(2)}) \cup (V_{m+1}^{(2)} \cup \partial V_{m+1}^{(2)})$ ;
- (ii)  $\varepsilon V_m^{(1)} + S^{m\delta+t}x \subset G$  for all  $t \in [0, \delta]$  and all  $\varepsilon \in [0, \varepsilon_0]$ ;
- (iii)  $\varepsilon V_m^{(2)} + S^{m\delta}x \subset G_\varepsilon \cap U_{2\varepsilon}(S^{m\delta}x)$  for all  $\varepsilon \in [0, \varepsilon_0]$ .

The main step in the proof of Theorem 3.1 is the following result.

LEMMA 3.1. *There is  $q > 0$  such that for all  $m = 0, 1, 2, \dots$  one has*

$$(3.7) \quad \inf_{z \in \varepsilon V_m^{(2)} + S^{m\delta}x} P_z^\varepsilon \{x_\delta^\varepsilon \in \varepsilon V_{m+1}^{(2)} + S^{(m+1)\delta}x \text{ and } \tau > \delta\} \geq q,$$

provided  $0 < \varepsilon \leq \varepsilon_0$ , where, recall,  $\tau$  is the exit time from  $G$  for the process  $x_t^\varepsilon$ .

PROOF. Let  $A(z)$  be the matrix of coefficients of the operator  $L$  in second order derivatives and  $b(z)$  be the vector of coefficients in first order derivatives, i.e.,

$$L = \frac{1}{2}(A(z)\nabla, \nabla) + (b(z), \nabla).$$

The process  $x_t^\varepsilon$  satisfies the following stochastic differential equation:

$$(3.8) \quad dx_t^\varepsilon = \varepsilon \sigma(x_t^\varepsilon)dw_t + (\varepsilon^2 b(x_t^\varepsilon) + B(x_t^\varepsilon))dt,$$

where  $\sigma(z)\sigma^*(z) = A(z)$  and  $w_t = (w_t^1, \dots, w_t^n)$  is the Wiener process.

For any  $m = 0, 1, 2, \dots$  set  $y_m^\varepsilon(t) = x_t^\varepsilon - S^{m\delta+t}x$ . Let  $z_m^\varepsilon(t)$  be the solution of the stochastic differential equation

$$(3.9) \quad dz_m^\varepsilon(t) = \varepsilon \sigma(z_m^\varepsilon(t) + S^{m\delta+t}x)dw_t + \varepsilon^2 b(z_m^\varepsilon(t) + S^{m\delta+t}x)dt.$$

The processes  $y_m^\varepsilon(t)$  and  $z_m^\varepsilon(t)$  differ just in drift, hence by Girsanov's formula (see, chapter 7 of [2]) and the properties of the domains  $V_m^{(1)}$  and  $V_m^{(2)}$  one gets

$$\begin{aligned}
 & P_z^\varepsilon \{x_\delta^\varepsilon \in \varepsilon V_{m+1}^{(2)} + S^{(m+1)\delta}x \text{ and } \tau > \delta\} \\
 & \cong P_z^\varepsilon \{x_\delta^\varepsilon \in \varepsilon V_{m+1}^{(2)} + S^{(m+1)\delta}x \text{ and } x_t^\varepsilon \in \varepsilon V_m^{(1)} + S^{m\delta+t}x \text{ for all } t \in [0, \delta]\} \\
 (3.10) \quad & = P_{z_m,0}^\varepsilon \{y_m^\varepsilon(\delta) \in \varepsilon V_{m+1}^{(2)} \text{ and } y_m^\varepsilon(t) \in \varepsilon V_m^{(1)} \text{ for all } t \in [0, \delta]\} \\
 & = E_{z_m,0}^\varepsilon \chi_{z_m^\varepsilon(\delta) \in \varepsilon V_{m+1}^{(2)}} \chi_{z_m^\varepsilon(t) \in \varepsilon V_m^{(1)} \text{ for all } t \in [0, \delta]} \frac{d\mu_{y_m^\varepsilon}}{d\mu_{z_m^\varepsilon}}(z_m^\varepsilon) \\
 & = E_{z_m/\varepsilon,0}^\varepsilon \chi_{v_m^\varepsilon(\delta) \in V_{m+1}^{(2)}} \chi_{v_m^\varepsilon(t) \in V_m^{(1)} \text{ for all } t \in [0, \delta]} \frac{d\mu_{y_m^\varepsilon}}{d\mu_{z_m^\varepsilon}}(\varepsilon v_m^\varepsilon),
 \end{aligned}$$

where  $z_m = z - S^{m\delta}x$ ,  $v_m^\varepsilon(t) = z_m^\varepsilon/\varepsilon$ ,  $P_{y,0}^\varepsilon$  and  $E_{y,0}^\varepsilon$  denote the probability and the expectation of nonhomogeneous processes starting in zero time at  $y$ , and

$$(3.11) \quad \frac{d\mu_{y_m^\varepsilon}}{d\mu_{z_m^\varepsilon}}(\varepsilon v_m^\varepsilon) = \exp \left\{ \frac{1}{\varepsilon} \int_0^\delta \sum_{i=1}^n h_i(t, \omega) dw_i^i - \frac{1}{2\varepsilon^2} \int_0^\delta \sum_{i=1}^n h_i^2(t, \omega) dt \right\},$$

where  $h(t, \omega) = (h_1(t, \omega), \dots, h_n(t, \omega))$  defined by the formula

$$h(t, \omega) = \sigma^{-1}(\varepsilon v_m^\varepsilon(t) + S^{m\delta+t}x)(B(\varepsilon v_m^\varepsilon(t) + S^{m\delta+t}x) - B(S^{m\delta+t}x)).$$

Let  $\theta_m$  be the exit time for the process  $v_m^\varepsilon(t)$  from  $V_m^{(1)}$ ; then (see [2])

$$\begin{aligned}
 E_v^\varepsilon \chi_{\theta_m > \delta} \left( \int_0^\delta \sum_{i=1}^n h_i(t, \omega) dw_i^i \right)^2 & \leq E_v^\varepsilon \left( \int_0^{\min(\delta, \theta_m)} \sum_{i=1}^n h_i(t, \omega) dw_i^i \right)^2 \\
 & = E_v^\varepsilon \int_0^{\min(\delta, \theta_m)} \sum_{i=1}^n h_i^2(t, \omega) dt.
 \end{aligned}$$

Therefore by (3.11) and Chebyshev's inequality we easily get that for any  $v \in V_m^{(2)}$  and each  $a > 0$ ,

$$\begin{aligned}
 & P_{v,0}^\varepsilon \left\{ v_m^\varepsilon(t) \in V_m^{(1)} \text{ for all } t \in [0, \delta] \text{ and } \frac{d\mu_{y_m^\varepsilon}}{d\mu_{z_m^\varepsilon}}(\varepsilon v_m^\varepsilon) < e^{-a} \right\} \\
 (3.12) \quad & = P_{v,0}^\varepsilon \left\{ \theta_m > \delta \text{ and } \left( \frac{1}{2\varepsilon^2} \int_0^\delta \sum_{i=1}^n h_i^2(t, \omega) dt - \frac{1}{\varepsilon} \int_0^\delta \sum_{i=1}^n h_i(t, \omega) dw_i^i \right) > a \right\} \\
 & \leq \frac{M}{a^2},
 \end{aligned}$$

where  $M$  depends just on the upper bounds of the norm  $\|\sigma^{-1}(z)\|$  and the derivatives of the vector function  $B(z)$ , but not on  $\varepsilon$  and  $a$ .

On the other hand, by the definition of  $v_m^\varepsilon(t)$  and the properties of the domains  $V_m^{(1)}$  and  $V_m^{(2)}$  one can easily see from the uniform estimates from below

of the fundamental solution of the parabolic equation in a bounded domain given in theorem 8 of [1] that if  $v \in V_m^{(2)}$  then

$$(3.13) \quad P_{\varepsilon,0}^\varepsilon\{v_n^\varepsilon(\delta) \in V_{m+1}^{(2)} \text{ and } v_m^\varepsilon(t) \in V_m^{(1)} \text{ for all } t \in [0, \delta]\} \geq \rho > 0,$$

for some constant  $\rho > 0$  independent of  $m, \varepsilon$  and  $v \in V_m^{(2)}$ . Taking  $z \in \varepsilon V_m^{(2)} + S^{m\delta}x$  in (3.10) we obtain that  $z_m/\varepsilon \in V_m^{(2)}$  in (3.10). Therefore setting  $a = 2M/\rho$  one gets (3.7) by (3.10), (3.12) and (3.13) with  $q = \frac{1}{2}\rho \exp(-\sqrt{2M}/\rho)$ .

Now we can complete the proof of Theorem 3.1. By the Markov property for  $z \in \varepsilon V_0^{(2)} + x$  one has

$$(3.14) \quad \begin{aligned} &P_z^\varepsilon\{\tau > k\delta\} \\ &= E_z^\varepsilon \chi_{\tau > \delta} E_{x_\delta^\varepsilon}^\varepsilon \chi_{\tau > \delta} \cdots E_{x_{k\delta}^\varepsilon}^\varepsilon \chi_{\tau > \delta} \\ &\geq E_z^\varepsilon \chi_{\tau > \delta} \chi_{x_\delta^\varepsilon \in \varepsilon V_1^{(2)} + S^\delta x} E_{x_\delta^\varepsilon}^\varepsilon \chi_{\tau > \delta} \chi_{x_\delta^\varepsilon \in \varepsilon V_2^{(2)} + S^{2\delta} x} \cdots E_{x_{k\delta}^\varepsilon}^\varepsilon \chi_{\tau > \delta} \chi_{x_{k\delta}^\varepsilon \in \varepsilon V_k^{(2)} + S^{k\delta} x} \\ &\geq \left[ \inf_{m=0,1,\dots} \inf_{z \in \varepsilon V_m^{(2)} + S^{m\delta} x} P_z^\varepsilon\{x_\delta^\varepsilon \in \varepsilon V_{m+1}^{(2)} + S^{(m+1)\delta} x \text{ and } \tau > \delta\} \right]^k \\ &\geq q^k. \end{aligned}$$

Hence, by (3.3) for all  $\varepsilon \leq \varepsilon_0$ ,

$$(3.15) \quad \lambda^\varepsilon \geq \frac{1}{\delta} \ln q$$

that contradicts (3.4) and proves Theorem 3.1.

Notice that the function  $u^\varepsilon(x) = E_x^\varepsilon \tau$  is the solution of the problem (see [2])

$$(3.16) \quad L^\varepsilon u^\varepsilon = -1, \quad u^\varepsilon|_{\partial G} = 0.$$

The second part of Theorem 2.1 can be amplified as follows.

**THEOREM 3.2.** (a) *If for some  $x \in G$ ,*

$$\limsup_{\varepsilon \rightarrow 0} u^\varepsilon(x) = \infty,$$

*then the dynamical system  $S^t$  has a nonempty invariant set  $\Lambda(G) \subset G \cup \partial G$ ;*

(b) *If for any  $x \in G$ ,*

$$(3.17) \quad \liminf_{\varepsilon \rightarrow 0} u^\varepsilon(x) < \infty,$$

*then the open domain  $G$  contains no invariant with respect to  $S^t$  closed subset;*

(c) *The item (b) cannot be improved, i.e., the case when for any  $x \in G$*



$$(3.18) \quad \limsup_{\varepsilon \rightarrow 0} u^\varepsilon(x) < \infty$$

and  $\Lambda(G) \neq \emptyset$  is possible.

PROOF. The item (a) follows immediately from the item (b) of Theorem 2.1.

Suppose now that  $G$  contains an invariant closed subset  $\Lambda$ . Then there is positive  $\delta = \inf_{x \in \Lambda} \text{dist}(x, \partial G)$  and (2.9) is also true. Therefore one can easily get from [7] that for any  $x \in \Lambda$  and  $N > 0$

$$(3.19) \quad P_x^\varepsilon\{\tau < N\} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

But

$$(3.20) \quad E_x^\varepsilon \tau \geq \sum_{m=1}^{\infty} (m-1) P_x^\varepsilon\{(m-1) \leq \tau < m\} \geq N P_x^\varepsilon\{\tau \geq N\}.$$

Thus by (3.19),

$$\liminf_{\varepsilon \rightarrow 0} E_x^\varepsilon \tau \geq N$$

for any  $N$  and so

$$\liminf_{\varepsilon \rightarrow 0} E_x^\varepsilon \tau = \infty$$

that contradicts (3.17) and proves the item (b) of Theorem 3.2.

Now let us describe the example which satisfies (3.18) and  $\Lambda(G) \neq \emptyset$ . Let  $n = 2$ ,

$$(3.21) \quad L^\varepsilon = \frac{1}{2} \varepsilon^2 \left( \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} \right) - x_2 \frac{\partial}{\partial x_1} + x_1 \frac{\partial}{\partial x_2}$$

and  $G = \{(x_1, x_2) : (x_1 - 1)^2 + x_2^2 < 1\}$ .

In this case  $\Lambda(G)$  is the one point  $(0, 0)$  and for any  $x = (x_1, x_2)$ ,

$$(3.22) \quad S^t x = \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}.$$

Therefore for each  $x \in G$  there is  $\hat{t}(x) \in [\pi/2, 2\pi]$  such that  $S^{\hat{t}(x)} x \notin G \cup \partial G$ . Let  $p^\varepsilon(t, x, y)$  be the transition density of the process  $x_t^\varepsilon$  generated by  $L^\varepsilon$  in the whole plane  $R^2$ . Then

$$(3.23) \quad p^\varepsilon(t, x, y) = \frac{1}{2\pi\varepsilon^2} \exp \left\{ -\frac{1}{2\varepsilon^2} |y - S^t x|^2 \right\}.$$

If  $y \in U_\varepsilon(S^{i(x)}x)$ , then by (3.23)

$$(3.24) \quad p^\varepsilon(t, x, y) \geq (2\pi \sqrt{e} \varepsilon^2)^{-1}.$$

The area of  $U_\varepsilon(S^{i(x)}x) \cap (R^2 \setminus G)$  is greater than  $\pi \varepsilon^2/2$  and by (3.24) one gets

$$(3.25) \quad \begin{aligned} P_x^\varepsilon\{\tau \leq 2\pi\} &\geq P_x^\varepsilon\{\tau \leq \tilde{t}(x)\} \\ &\geq P_x^\varepsilon\{x_{\tilde{t}(x)}^\varepsilon \notin G\} \\ &\geq P_x^\varepsilon\{x_{\tilde{t}(x)}^\varepsilon \in U_\varepsilon(S^{i(x)}x) \cap (R^2 \setminus G)\} \\ &\geq (4\sqrt{e})^{-1}. \end{aligned}$$

Thus  $P_x^\varepsilon\{\tau > 2\pi\} \leq 1 - (4\sqrt{e})^{-1}$  and using the Markov property in the same way as in (2.11) we obtain

$$(3.26) \quad P_x^\varepsilon\{\tau > 2\pi m\} \leq (1 - (4\sqrt{e})^{-1})^m.$$

Finally,

$$E_x^\varepsilon \tau \leq 2\pi \sum_{m=1}^{\infty} P_x^\varepsilon\{\tau > 2\pi(m-1)\} \leq 8\pi \sqrt{e} < \infty$$

that gives (3.18) in spite of  $\Lambda(G) = \{(0, 0)\} \neq \emptyset$ .

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